Serial Nr.: 10/699,490

Art Unit: 2856

03222-URS

AMENDMENTS TO THE ABSTRACT:

The present invention relates to A silicon dual inertial sensor sensors made of a (110) silicon chip. The invention chip comprises at least [[an]] a proof-mass, which is connected to [[an]] a corresponding inner frame with a plurality of sensing resilient beams to make it easier for [[said]] the proof-mass to move perpendicular to the surface of [[said]] the silicon chip (defined as z-axis), and each inner frame is connected to [[the]] an outer frame with a plurality of driving resilient beams, or connected to [[the]] common connection beam beams, which [[is]] are then connected to a central anchor with [[the]] common resilient supporting beams beam to make it easier for [[said]] the inner frame to move in parallel with the surface of [[said]] the silicon chip (defined as y-axis). Each inner frame is driven by a driver to move in an opposite direction along the y-axis, and also move the proof-mass in the opposite direction along the y-axis, if y-axis. If there is a rotation rate input along the x-axis, it will generate generates a Coriolis force to make each [[said]] proof-mass [[to]] move in the opposite direction of the z-axis; if z-axis. If an acceleration is input along the z-axis, the specific force will move the [[said]] proofmasses with the same direction; when said proof-mass direction. When the proof-masses move or oscillate, the capacitance of the capacitor formed with sensing electrodes will change due to the change of distance; hence the of the distance. The moving distance can be obtained by measuring the change of eapacitance; as the capacitance. Because the rotation rate outputs an alternating signal, and the acceleration outputs a direct signal, they can be separated with signal processing. The present-invention utilizes the deep vertical etching characteristics of the (110) silicon chip is utilized to make the driving

Serial Nr.: 10/699,490

Art Unit: 2856

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03222-URS

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beam in order to control the driving resonance frequency more precisely, and improve improves the yield rate and the performance of the gyroscope.